Adaptive *hp*-FEM for Eigenproblems

Model problem:

 $-\Delta u + b \cdot \nabla u + cu = \lambda u, \quad u = 0 \text{ on } \partial \Omega$

where $b \in [L^{\infty}(\Omega)]^2$ and $c \in L^{\infty}(\Omega)$ is non-negative.

- P. Solin, S. Giani: Adaptive hp-FEM for Nonsymmetric Eigenvalue Problems. Computing, accepted.
- P. Solin, S. Giani: An Iterative Finite Element Method for Elliptic Eigenvalue Problems, J. Comp. Appl. Math. 236 (2012) 4582-4599.

◆□▶ ◆□▶ ◆三▶ ◆三▶ ◆□▶ ◆□

Traditional Approach

Call generalized eigensolver after each adaptivity step.



- Ordering of eigenvectors may change between adaptivity steps.
- For repeated eigenvalues, it may return an arbitrary linear combination.
- One mesh cannot be optimal for *n* different eigenfunctions.

→ ∃ →

크

Call generalized eigensolver only once:

- Pursue each eigenvalue-eigenvector pair on an individual mesh.
- Adaptive *hp*-FEM combined with Newton or Picard.
- Keeps focus on the selected eigenvalue-eigenvector pair.
- Avoids linear combinations in case of repeated eigenvalues.

$$Au^0 = \lambda^0 Bu^0$$

$$Au^{m+1} := \lambda^m Bu^m$$

$$\lambda^{m+1} := \frac{(u^{m+1})^t Au^{m+1}}{(u^{m+1})^t Bu^{m+1}}$$

$$m := m+1$$

Eigenfunction from coarse mesh used as initial condition on globally refined mesh. Adaptivity: Based on solution pairs, same as in standard *hp*-FEM.

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

$$0 = f(x, \lambda) := \begin{pmatrix} Ax & - & \lambda Bx \\ x^T Bx & - & 1 \end{pmatrix}$$

Adaptivity - same as with Picard.

< 日 > < 回 > < 回 > < 回 > < 回 > <

æ

Example 1



Eigenfunctions #1 and #2

< 🗗

ъ

æ

Example 2





hp-FEM group, University of Nevada, Reno Selected Topics in Adaptive Higher-Order FEM

æ